

## Appendix D – Basic Roadway Geometry Information

### USE OF CARTESIAN SYSTEMS

The following summarizes some of the basic formulas for Cartesian coordinate systems.

For implicitly distinct points:

P(1) represented by coordinates  $(X_1, Y_1)$

P(2) represented by coordinates  $(X_2, Y_2)$

P(3) represented by coordinates  $(X_3, Y_3)$  etc.

P(1), P(2) and P(3) lie on the same line (are colinear) if

$$Y_3 = Y_2 + \frac{(X_3 - X_2)(Y_1 - Y_2)}{(X_1 - X_2)} \quad \text{OR} \quad X_3 = X_2 + \frac{(Y_3 - Y_2)(X_1 - X_2)}{(Y_1 - Y_2)}$$

$$\text{OR} \quad \det \begin{vmatrix} X_1 & Y_1 & 1 \\ X_2 & Y_2 & 1 \\ X_3 & Y_3 & 1 \end{vmatrix} = 0$$

Distance from P(1) to P(2) (in the horizontal plane)

$$\sqrt{(X_2 - X_1)^2 + (Y_2 - Y_1)^2}$$

The Euclidean norm (including difference in elevation)

$$\sqrt{(X_2 - X_1)^2 + (Y_2 - Y_1)^2 + (\text{Elev.}_2 - \text{Elev.}_1)^2}$$

Line through P(1) and P(2) is parallel to line through P(3) and P(4) if

$$(X_1 - X_2)(Y_3 - Y_4) = (X_3 - X_4)(Y_1 - Y_2)$$

Line through P(1) and P(2) is perpendicular to line through P(3) and P(4) if:

$$(X_1 - X_2)(X_3 - X_4) = (Y_1 - Y_2)(Y_4 - Y_3)$$

Area of triangle with vertices P(1), P(2) and P(3)

$$\left| (X_1 Y_2 + X_2 Y_3 + X_3 Y_1 - X_1 Y_3 - X_2 Y_1 - X_3 Y_2) \right| / 2$$

$$\left| ((X_1 - X_2)(Y_3 - Y_2) - (X_3 - X_2)(Y_1 - Y_2)) \right| / 2$$

Area of quadrilateral with sequential vertices P(1), P(2), P(3) and P(4)

$$\left| ((X_1 Y_2 + X_2 Y_3 + X_3 Y_4 + X_4 Y_1 - X_1 Y_4 - X_2 Y_1 - X_3 Y_2 - X_4 Y_1)) \right| / 2$$

Distance of P(3) from the line through P(1) and P(2) is equal to twice the area of triangle P(1), P(2), P(3) divided by distance from P(1) to P(2)

$$\frac{\left| ((X_1 - X_2)(Y_3 - Y_2) - (X_3 - X_2)(Y_1 - Y_2)) \right|}{\sqrt{(X_2 - X_1)^2 + (Y_2 - Y_1)^2}}$$

Transit at P(0), the angle turned from the line (parallel to Y-axis) to sight P(1) is given by

$$\theta = \text{Arctan} \frac{X_1 - X_0}{Y_1 - Y_0}$$

The angle turned from sight on P(1) to sight P(2) is given by

$$\theta = \text{Arctan} \frac{(Y_1 - Y_0)(X_2 - X_0) - (X_1 - X_0)(Y_2 - Y_0)}{(X_1 - X_0)(X_2 - X_0) + (Y_1 - Y_0)(Y_2 - Y_0)}$$

If  $\tan(\theta)$  is  $> 0$ ,  $\theta$  may be either to the right  $0^\circ < \theta < 90^\circ$  or to the left  $-180^\circ < \theta < -90^\circ$ .

If  $\tan(\theta)$  is  $< 0$ ,  $\theta$  may be either to the left  $-90^\circ < \theta < 0^\circ$  or the right  $90^\circ < \theta < 180^\circ$ .

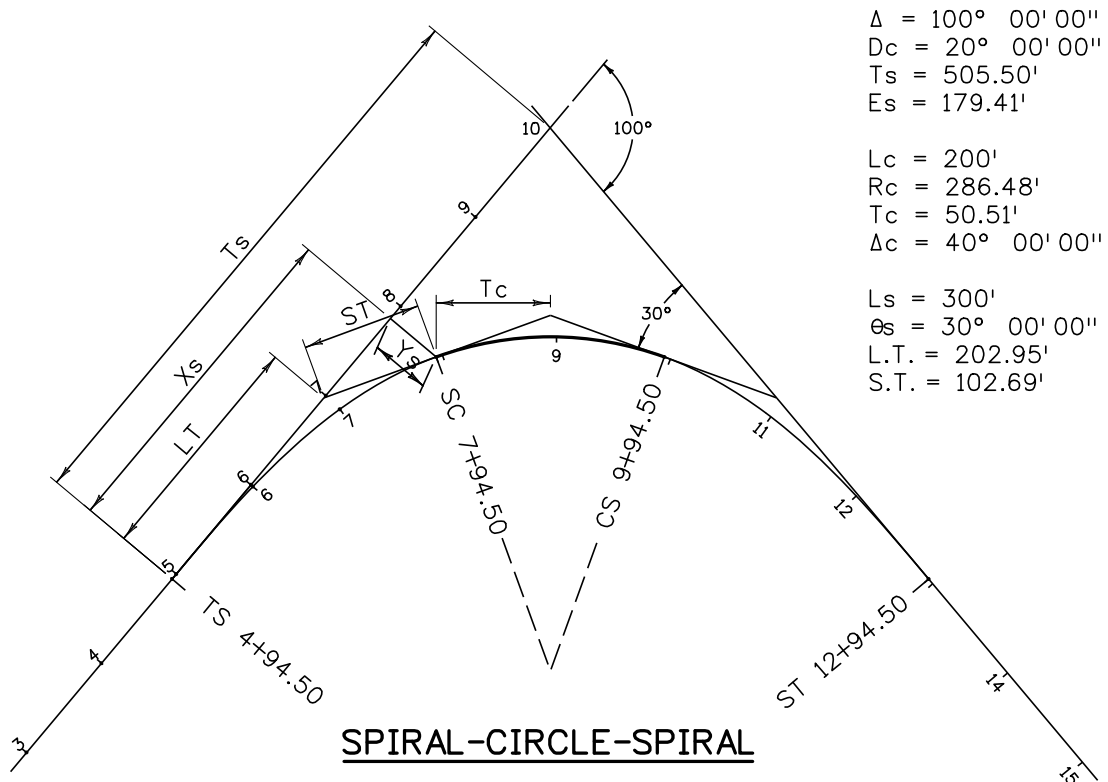
PI Point of intersection of tangents  
 TS Tangent to spiral point  
 SC Spiral to circle point  
 CS Circle to spiral point  
 ST Spiral to tangent point

$\Delta$  = Total deflection angle of curve  
 $\theta_s$  = Deflection angle of spiral  
 $T_s$  = Distance from ST to PI  
 $E_s$  = External distance from PI to center of circular portion of curve  
 $L_s$  = Length of spiral  
 $L_t$  = Distance from ST or TS to PI of spiral  
 $St$  = Distance from PI of spiral to SC or CS  
 $D_c$  = Degree of curve of circular portion  
 $T_c$  = Distance from S.C. or C.S. to P.I of circular portion  
 $L_c$  = Arc length of circular portion S.C. to C.S.  
 $R_c$  = Radius of circular Portion

$$D = \frac{L}{L_s} \times D_c ; \text{Relationship between } D_c \text{ and the curvature of the spiral}$$

$$\theta_s = \frac{L_s}{200} \times D_c ; \text{Relationship between } \theta_s, L_s, \text{ and } D_c$$

$$\theta = \frac{L^2}{L_s^2} \times \theta_s ; \text{Angle at any length (L) along spiral with respect to } L_s \text{ and } \theta$$



- TS Point of change from tangent to spiral
- ST Point of change from spiral to tangent
- SC Point of change from spiral to circle
- CS Point of change from circle to spiral
- l Spiral arc length from TS to any point
- $l_s$  total length of spiral from TS to SC
- $\theta$  Central angle of spiral arc l
- $\theta_s$  Central angle of spiral arc  $l_s$ , called "spiral angle"
- D Degree of curve of the spiral at any point
- R Radius of curve of the spiral at any point
- $D_c$  Degree of curve of the shifted circle to which the spiral becomes tangent at the SC
- $R_c$  The radius of the circle
- L.T. Long tangent distance of spiral only
- S.T. Short tangent distance of spiral only
- p Offset distance from the tangent of P.C. of circular curve produced
- k Distance from T.S. to point on tangent opposite the P.C. of the circular curve produced
- x,y Coordinates at any point on the spiral
- $x_s, y_s$  Coordinates at the S.C. or C.S.

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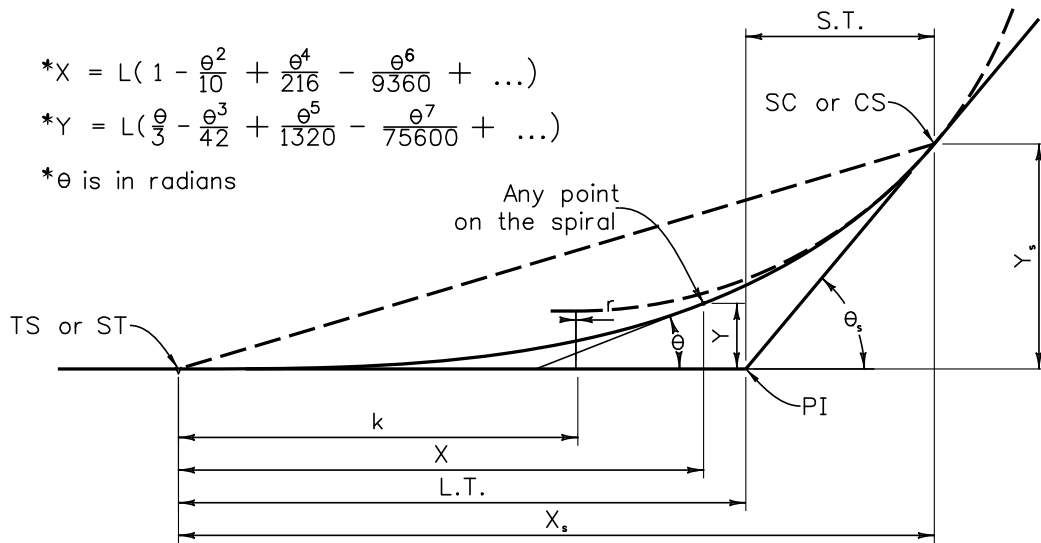
$$\theta_s = \frac{L_s}{200} \times D_c ; \text{Relationship between } \theta_s, L_s, \text{ and } D_c$$

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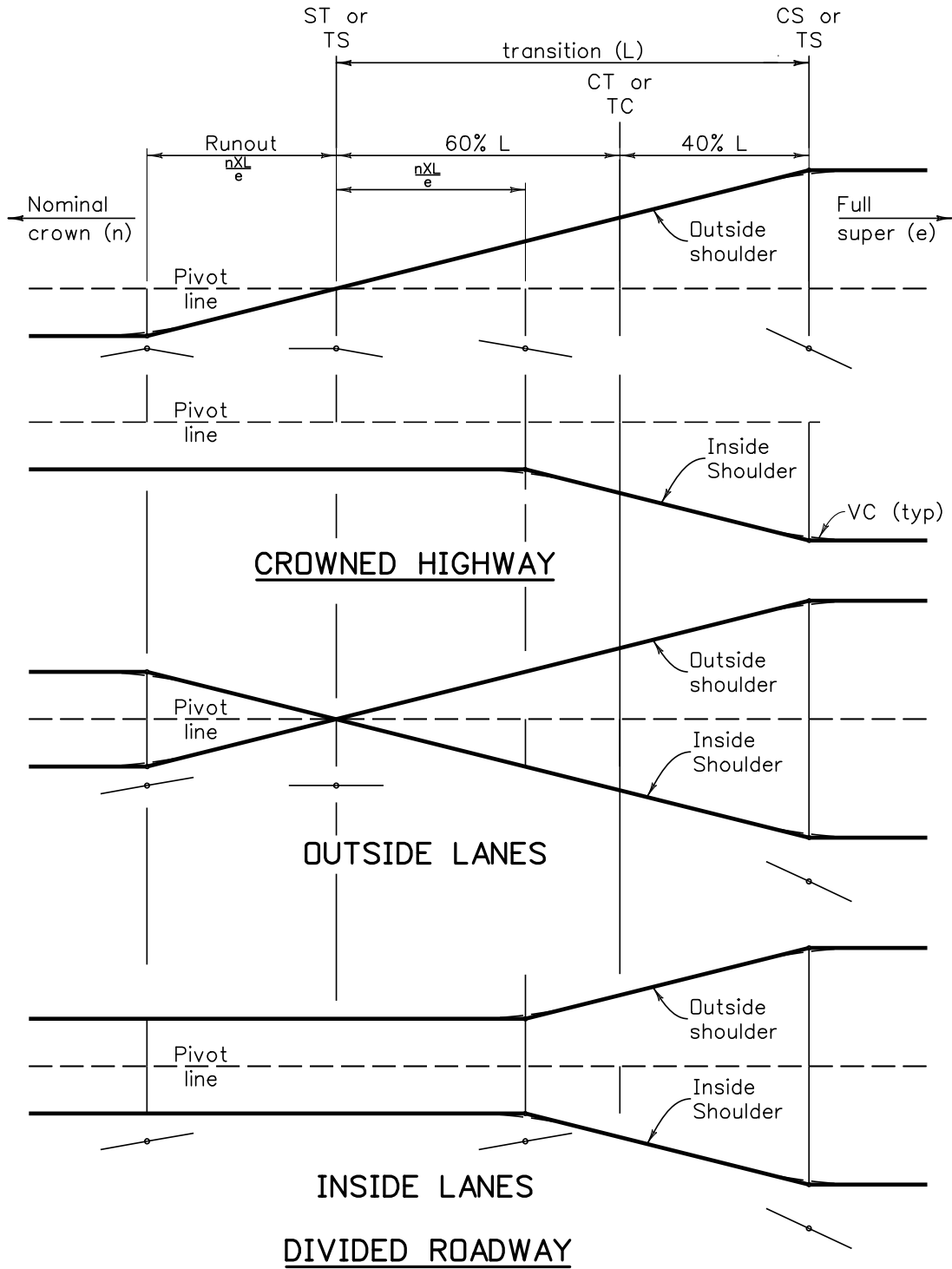
$$*X = L \left( 1 - \frac{\theta^2}{10} + \frac{\theta^4}{216} - \frac{\theta^6}{9360} + \dots \right)$$

$$*Y = L \left( \frac{\theta}{3} - \frac{\theta^3}{42} + \frac{\theta^5}{1320} - \frac{\theta^7}{75600} + \dots \right)$$

\* $\theta$  is in radians



**SPIRAL EXAMPLE**



SUPERELEVATION DIAGRAMS